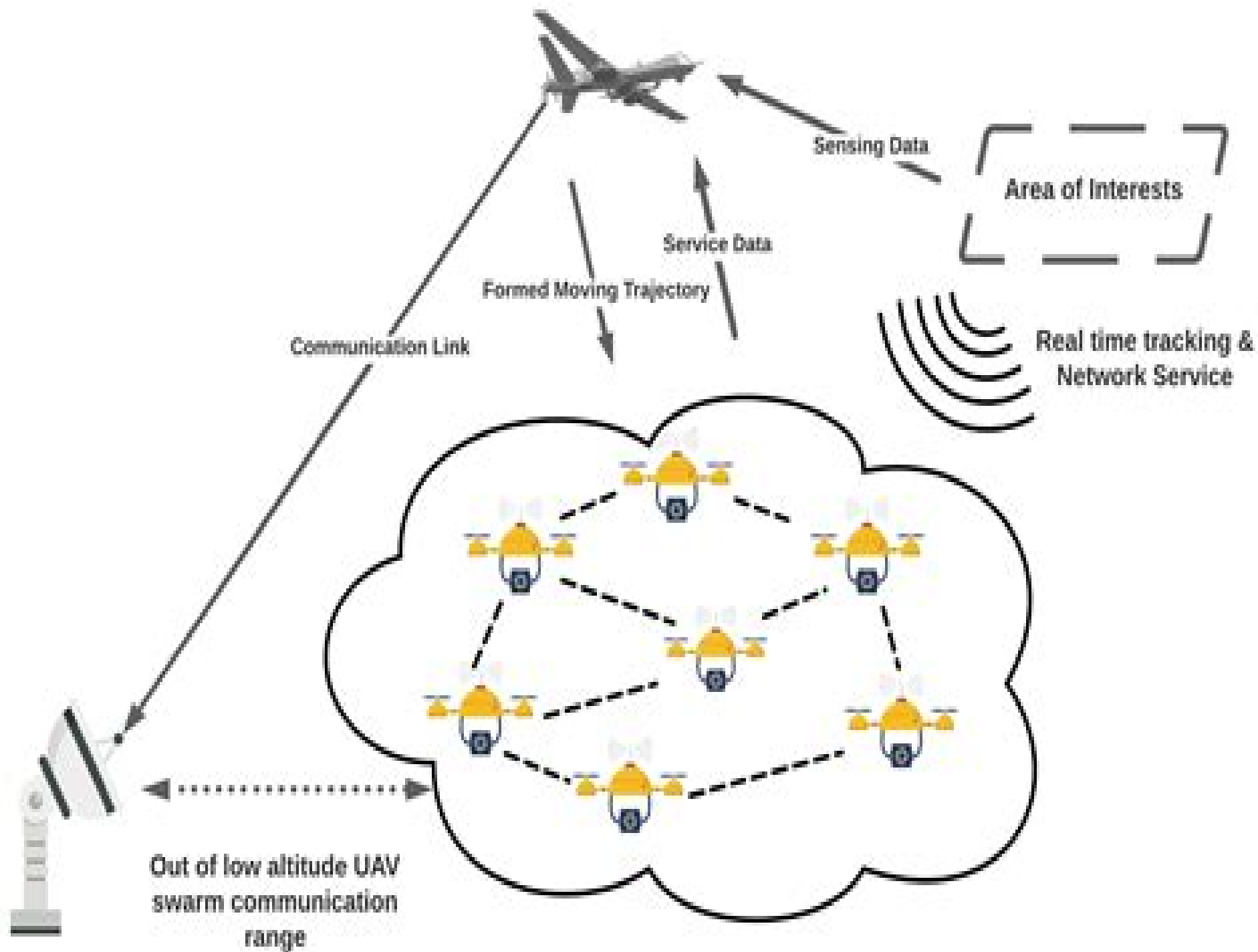




Swarm Intelligence For Autonomous Uav Control

David Kirk



Swarm Intelligence For Autonomous Uav Control:

Swarm Intelligence for Autonomous UAV Control ,2005 Unmanned Aerial Vehicles UAVs are becoming vital warfare platforms because they significantly reduce the risk of human life while accomplishing important missions A UAV can be used for example as stand in sensor for the detection of mobile low probability of intercept battlefield surveillance and fire control emitters With many UAVs acting together as a swarm the location and frequency characteristics of each emitter can be accurately determined to continuously provide complete battlefield awareness The swarm should be able to act autonomously while searching for targets and relaying the information to all swarm members In this thesis two methods of autonomous control of a UAV swarm were investigated The first method investigated was the Particle Swarm Optimization PSO algorithm This technique uses a non linear approach to minimize the error between the location of each particle and the target by accelerating particles through the search space until the target is found When applied to a swarm of UAVs the PSO algorithm did not produce the desired performance results The second method used a linear algorithm to determine the correct heading and maneuver the swarm toward the target at a constant velocity This thesis shows that the second approach is more practical to a UAV swarm New results are shown to demonstrate the application of the algorithm to the swarm movement

Unmanned Aerial Vehicles Swarm for Protecting Smart Cities Oroos Arshi, Inam Ullah Khan, Keshav Kaushik, Nadeem Iqbal, Inam Ullah, Khadija Slimani, 2025-02-28 Explore the intersection between unmanned aerial vehicles UAVs and the evolving landscape of smart cities With the increasing integration of technology into urban environments there is a growing need to understand how UAV swarms can contribute to the safety efficiency and resilience of these complex urban ecosystems The book aims to provide a technical understanding of UAV swarms and their applications within the context of smart cities It begins by laying the groundwork with an introduction to UAV swarms and smart cities establishing the foundational concepts and motivations behind their integration As the book progresses it delves into various aspects of smart cities exploring concepts technologies and challenges inherent in their development and operation This includes discussions on cloud computing cybersecurity machine learning applications surveillance and monitoring systems urban planning and infrastructure management It also examines the integration of IoT devices with UAV swarms highlighting the synergies between these emerging technologies and their potential impact on urban environments The book examines cutting edge topics such as edge computing blockchain applications 5G integration and augmented reality virtual reality AR VR visualization techniques in the context of UAV swarm operations It concludes with reflections on innovations and future directions offering insights into the evolving landscape of UAV swarm technologies and their implications for the protection and advancement of smart cities The book serves as a comprehensive guide for researchers practitioners and policymakers interested in understanding the technical social and economic dimensions of UAV swarm technology within the context of smart city development and management What You Will Learn Identify practical applications of UAV swarms in surveillance

monitoring urban planning disaster management and infrastructure resilience Gain comprehensive understanding of UAV swarms by exploring diverse disciplines Apply insights from emerging technologies like cloud computing machine learning blockchain IoT devices and so on to UAV swarm technology Who Is This Book For This book appeals to a wide range of readers with different interests and backgrounds including researchers policymakers industry stakeholders practitioners experts and general fans who are curious in the confluence of smart cities with UAV swarm technologies with little to no experience or knowledge of UAV swarms

Swarm Intelligence Heiko Hamann,Marco Dorigo,Leslie Pérez Cáceres,Andreagioanni Reina,Jonas Kuckling,Tanja Katharina Kaiser,Mohammad Soorati,Ken Hasselmann,Eduard Buss,2024-09-14 This book constitutes the proceedings of the 14th International Conference on Swarm Intelligence ANTS 2024 which took place in Konstanz Germany during October 9 11 2024 The 14 full papers and 5 short papers included in this book were carefully reviewed and selected from 33 submissions They deal with self organizing processes both in nature and in artificial systems

HCI International 2021 - Late Breaking Papers: Multimodality, eXtended Reality, and Artificial Intelligence Constantine Stephanidis,Masaaki Kurosu,Jessie Y. C. Chen,Gino Fragomeni,Norbert Streitz,Shin'ichi Konomi,Helmut Degen,Stavroula Ntoa,2021-11-10 This book constitutes late breaking papers from the 23rd International Conference on Human Computer Interaction HCII 2021 which was held in July 2021 The conference was planned to take place in Washington DC USA but had to change to a virtual conference mode due to the COVID 19 pandemic A total of 5222 individuals from academia research institutes industry and governmental agencies from 81 countries submitted contributions and 1276 papers and 241 posters were included in the volumes of the proceedings that were published before the start of the conference Additionally 174 papers and 146 posters are included in the volumes of the proceedings published after the conference as Late Breaking Work papers and posters The contributions thoroughly cover the entire field of HCI addressing major advances in knowledge and effective use of computers in a variety of application areas

New Developments and Environmental Applications of Drones Tarmo Lipping,Petri Linna,Nathaniel Narra,2021-10-29 This volume presents the conference proceedings from FinDrones2020 The book highlights recent developments in drone technology by experts academicians and entrepreneurs for applications in agriculture forestry and other industries Emphasis is placed on contextualizing the conference presentations and content to Finland and the unique challenges typical to this region The work will be of interest to academicians and professionals involved in remote sensing applications of unmanned aerial vehicles as well as enthusiasts of drone technological developments

Research and Updates on the Use of Artificial Intelligence in Drone Technology T. Hikmet Karakoc,Khagani Abdullayev,Alper Dalkiran,Fuad Mirzayev,Elgun Aghayev,Bahadır Cinoğlu,2025-12-02 This book presents a collection of proceedings papers on unmanned systems which provides a comprehensive view of the latest research and insights The International Symposium on Unmanned Systems AI Design Efficiency ISUDEF 2024 is a gathering of researchers scientists engineers practitioners policymakers and students

working on topics in the unmanned aerial vehicle UAV systems industry and artificial intelligence AI The purpose of the symposium is to exchange information present new technologies and developments and discuss the future direction strategies and priorities in aviation and sustainability The papers cover a broad range of current issues in aviation including aerial naval and land applications avionics radar systems AI design and platform integration robotics and autonomous systems that provide innovative solutions to the challenges facing the UAV industry including civilian applications and homeland security

Nonlinear Control of Fixed-Wing UAVs with Time-Varying and Unstructured Uncertainties Michail G. Michailidis, Kimon P. Valavanis, Matthew J. Rutherford, 2020-02-21 This book introduces a comprehensive and mathematically rigorous controller design for families of nonlinear systems with time varying parameters and unstructured uncertainties Although the presented methodology is general the specific family of systems considered is the latest NextGen unconventional fixed wing unmanned aircraft with circulation control or morphing wings or a combination of both The approach considers various sources of model and parameter uncertainty while the controller design depends not on a nominal plant model but instead on a family of admissible plants In contrast to existing controller designs that consider multiple models and multiple controllers the proposed approach is based on the one controller fits all models within the unstructured uncertainty interval The book presents a modeling based analysis and synthesis approach with additive uncertainty weighting functions for accurate realization of the candidate systems This differs significantly from existing designs in that it is capable of handling time varying characteristics This research monograph is suitable for scientists engineers researchers and graduate students with a background in control system theory who are interested in complex engineering nonlinear systems

Applications of Machine Learning in UAV Networks Hassan, Jahan, Alsamhi, Saeed, 2024-01-17 Applications of Machine Learning in UAV Networks presents a pioneering exploration into the symbiotic relationship between machine learning techniques and UAVs In an age where UAVs are revolutionizing sectors as diverse as agriculture environmental preservation security and disaster response this meticulously crafted volume offers an analysis of the manifold ways machine learning drives advancements in UAV network efficiency and efficacy This book navigates through an expansive array of domains each demarcating a pivotal application of machine learning in UAV networks From the precision realm of agriculture and its dynamic role in yield prediction to the ecological sensitivity of biodiversity monitoring and habitat restoration the contours of each domain are vividly etched These explorations are not limited to the terrestrial sphere rather they extend to the pivotal aerial missions of wildlife conservation forest fire monitoring and security enhancement where UAVs adorned with machine learning algorithms wield an instrumental role Scholars and practitioners from fields as diverse as machine learning UAV technology robotics and IoT networks will find themselves immersed in a confluence of interdisciplinary expertise The book's pages cater equally to professionals entrenched in agriculture environmental studies disaster management and beyond

UAV Aerodynamics and Crop Interaction Imran, Jiyu

Li,2025-07-26 This book offers insights into how drone aerodynamics influence crop growth yield and resilience and explores the potential of UAV technology By bridging advanced engineering principles with precision agriculture it presents practical methods for optimizing UAV operations to enhance microclimates improve crop health and boost productivity Readers will find in depth analyses supported by compelling results clear case studies and high quality illustrations that vividly demonstrate the interaction between UAV downwash airflow and crop morphology Special features include detailed schematics data driven tables and a step by step guide to designing UAV systems tailored for agricultural applications This comprehensive approach ensures that readers not only understand the science but are also equipped to implement innovative techniques in real world scenarios The primary audience of this book includes undergraduates and graduate students crop scientists agronomists agricultural engineers UAV researchers policymakers and advanced students seeking to revolutionize sustainable farming practices through cutting edge drone technologies

Harnessing Digital Innovation for Air Transportation Yilmaz, Ayse Asli,2024-03-04 The aviation industry faces an unprecedented challenge the digital transformation revolution While digital technologies promise immense benefits in terms of efficiency safety and passenger experience they also bring forth intricate challenges Navigating through complex regulatory frameworks and safeguarding against cybersecurity risks has become a paramount concern for aviation professionals and academics alike The industry s future success hinges on its ability to adapt to this digital revolution while effectively managing the potential pitfalls it presents Harnessing Digital Innovation for Air Transportation emerges as a timely and comprehensive solution for academic scholars in aviation management It offers a profound exploration of how digital innovations are shaping various facets of aviation and provides in depth strategies to address the challenges presented by this digital revolution From understanding the impact of digital transformation to harnessing data analytics managing safety enhancing the passenger experience and delving into emerging technologies this book equips readers with the knowledge and tools to thrive in the digital age of aviation

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