



The Robotics Primer Intelligent Robotics And Autonomous Agents Series

**Ahmed Alruwaili, Sardar M. N.
Islam, Iqbal Gondal**



The Robotics Primer Intelligent Robotics And Autonomous Agents Series:

The Robotics Primer Maja J. Mataric, 2007-08-17 A broadly accessible introduction to robotics that spans the most basic concepts and the most novel applications for students teachers and hobbyists The Robotics Primer offers a broadly accessible introduction to robotics for students at pre university and university levels robot hobbyists and anyone interested in this burgeoning field The text takes the reader from the most basic concepts including perception and movement to the most novel and sophisticated applications and topics humanoids shape shifting robots space robotics with an emphasis on what it takes to create autonomous intelligent robot behavior The core concepts of robotics are carried through from fundamental definitions to more complex explanations all presented in an engaging conversational style that will appeal to readers of different backgrounds The Robotics Primer covers such topics as the definition of robotics the history of robotics Where do Robots Come From robot components locomotion manipulation sensors control control architectures representation behavior Making Your Robot Behave navigation group robotics learning and the future of robotics and its ethical implications To encourage further engagement experimentation and course and lesson design The Robotics Primer is accompanied by a free robot programming exercise workbook that implements many of the ideas on the book on iRobot platforms The Robotics Primer is unique as a principled pedagogical treatment of the topic that is accessible to a broad audience the only prerequisites are curiosity and attention It can be used effectively in an educational setting or more informally for self instruction The Robotics Primer is a springboard for readers of all backgrounds including students taking robotics as an elective outside the major graduate students preparing to specialize in robotics and K 12 teachers who bring robotics into their classrooms

Cybersecurity in Robotic Autonomous Vehicles Ahmed Alruwaili, Sardar M. N. Islam, Iqbal Gondal, 2025-03-21 Cybersecurity in Robotic Autonomous Vehicles introduces a novel intrusion detection system IDS specifically designed for AVs which leverages data prioritisation in CAN IDs to enhance threat detection and mitigation It offers a pioneering intrusion detection model for AVs that uses machine and deep learning algorithms Presenting a new method for improving vehicle security the book demonstrates how the IDS has incorporated machine learning and deep learning frameworks to analyse CAN bus traffic and identify the presence of any malicious activities in real time with high level of accuracy It provides a comprehensive examination of the cybersecurity risks faced by AVs with a particular emphasis on CAN vulnerabilities and the innovative use of data prioritisation within CAN IDs The book will interest researchers and advanced undergraduate students taking courses in cybersecurity automotive engineering and data science Automotive industry and robotics professionals focusing on Internet of Vehicles and cybersecurity will also benefit from the contents

Soft Robotics Cecilia Laschi, 2025-09-02 A comprehensive cutting edge treatment of soft robotics that brings conceptual structure to this fast moving field Soft robotics is quickly transforming corners of our world but as yet there has been no comprehensive treatment of the young field Filling this gap Soft Robotics offers a systematic approach to learning the subject

s essential ideas methods and techniques Cecelia Laschi takes a holistic view that integrates interdisciplinary material and provides a conceptual structure that can withstand the discipline s fast paced evolution Laschi first presents robotics basics and the commonly used bioinspired methods before covering materials and technologies for actuation and sensing modeling internal and external interactions and soft robot control with model based and learning based approaches Written by a pioneer of the field and honed by classroom experience this timely textbook is an essential roadmap for anyone studying soft robotics Comprehensive structured coverage of soft robotics from fundamentals to advanced techniques Pragmatic modular structure adapts to different curricula Suitable for advanced undergraduates graduate students and professionals Instructor resources include slides videos and exercises

Behavioural Production Robert Stuart-Smith,2024-07-15 Autonomous manufacturing and cyber physical systems are key enabling technologies of the Fourth Industrial Revolution IR4 which are currently being incorporated into the building design and construction industries These emerging IR4 technologies have the potential to effectively improve construction affordability and productivity address current and future building demand and reduce the environmental impact of the built environment However design approaches that make use of IR4 technologies are still relatively unexplored While automation such as mass production promotes standardised design solutions design thinking that embraces varying degrees of autonomy can lead to unique and considered approaches to design on an industrial scale Behavioural Production Semi Autonomous Approaches to Architectural Design Robotic Fabrication and Collective Robotic Construction explores design operating through the orchestration of spatiotemporal events A multi agent behaviour based approach to computation is employed in architectural design and extended to individual and swarm based robotic methods for additive manufacturing Behavioural Production seeks to expand our capacity to engage with the world at large through varying degrees of autonomy In an industrialised world where traditional craftsmanship has been marginalised and cannot scale to meet societal needs this book speculates a means to bring scalable forms of creativity into the act of making This is explored through the use of materials generative algorithms computer vision machine learning and robot systems as active agents in design conception and realisation The book presents a collection of ideas projects and methods developed in the author s design practices and research labs in the fields of architecture and computer science This body of work demonstrates that engaging with semi autonomous processes does not diminish authorship but rather expands it into new forms of design agency that seamlessly integrate with emerging manufacturing and construction technologies whilst authoring distinctive design character

Robotics For Engineers- Concepts And Tec Kailash Chandra Mahajan, Robotics for Engineers provides introductory but detailed study of robot design installation and maintenance It caters to the needs of the students by emphasizing the practical utility of robot in the field of engineering science and technology The book introduces the science and engineering of robotics and provides in depth coverage of mechanical and electrical manipulation For every topic the fundamental mathematical concepts and analytical tools required to develop the relevant

theory algorithms and programming have been discussed sufficiently ACL programming has been used for developing the robot programming In the current form this book is useful for undergraduates postgraduates and research scholar students for their course and research projects

Unmanned Systems of World Wars I and II H. R. Everett, 2015-11-06 The first comprehensive technical history of air land sea and underwater unmanned systems by a distinguished U S Navy roboticist Military drones have recently been hailed as a revolutionary new technology that will forever change the conduct of war And yet the United States and other countries have been deploying such unmanned military systems for more than a century Written by a renowned authority in the field this book documents the forgotten legacy of these pioneering efforts offering the first comprehensive historical and technical accounting of unmanned air land sea and underwater systems Focusing on examples introduced during the two world wars H R Everett meticulously traces their development from the mid nineteenth century to the early Cold War A pioneering Navy roboticist Everett not only describes these systems in detail but also reverse engineers the designs in order to explain how they operated in real world conditions of the time More than 500 illustrations photographs drawings and plans many of them never before published accompany the text Everett covers the evolution of early wire guided submersibles tracing the development of power propulsion communication and control radio controlled surface craft deployed by both Germany and Great Britain in World War I radio controlled submersibles radio controlled aircraft including the TDR 1 assault drone project in World War II which laid the groundwork for subsequent highly classified drone programs and remote controlled ground vehicles including the Wehrmacht s Goliath and Borgward demolition carriers

Neurorobotics Tiffany J. Hwu, Jeffrey L. Krichmar, 2022-11-29 An introduction to neurorobotics that presents approaches and design principles for developing intelligent autonomous systems grounded in biology and neuroscience Neurorobotics is an interdisciplinary field that draws on artificial intelligence cognitive sciences computer science engineering psychology neuroscience and robotics Because the brain is closely coupled to the body and situated in the environment neurorobots autonomous systems modeled after some aspect of the brain offer a powerful tool for studying neural function and may also be a means for developing autonomous systems with intelligence that rivals that of biological organisms This textbook introduces approaches and design principles for developing intelligent autonomous systems grounded in biology and neuroscience It is written for anyone interested in learning about this topic and can be used in cognitive robotics courses for students in psychology cognitive science and computer science Neurorobotics covers the background and foundations of the field with information on early neurorobots relevant principles of neuroscience learning rules and mechanisms and reinforcement learning and prediction neurorobot design principles grounded in neuroscience and principles of neuroscience research and examples of neurorobots for navigation developmental robotics and social robots presented with the cognitive science and neuroscience background that inspired them A supplementary website offers videos robot simulations and links to software repositories with neurorobot examples

Quantum Robotics Prateek Tandon, Stanley Lam, Ben Shih, Tanay

Mehta,Alex Mitev,Zhiyang Ong,2022-05-31 Quantum robotics is an emerging engineering and scientific research discipline that explores the application of quantum mechanics quantum computing quantum algorithms and related fields to robotics This work broadly surveys advances in our scientific understanding and engineering of quantum mechanisms and how these developments are expected to impact the technical capability for robots to sense plan learn and act in a dynamic environment It also discusses the new technological potential that quantum approaches may unlock for sensing and control especially for exploring and manipulating quantum scale environments Finally the work surveys the state of the art in current implementations along with their benefits and limitations and provides a roadmap for the future **Robot Ethics** Patrick

Lin,Keith Abney,George A. Bekey,2014-01-10 Prominent experts from science and the humanities explore issues in robot ethics that range from sex to war Robots today serve in many roles from entertainer to educator to executioner As robotics technology advances ethical concerns become more pressing Should robots be programmed to follow a code of ethics if this is even possible Are there risks in forming emotional bonds with robots How might society and ethics change with robotics This volume is the first book to bring together prominent scholars and experts from both science and the humanities to explore these and other questions in this emerging field Starting with an overview of the issues and relevant ethical theories the topics flow naturally from the possibility of programming robot ethics to the ethical use of military robots in war to legal and policy questions including liability and privacy concerns The contributors then turn to human robot emotional relationships examining the ethical implications of robots as sexual partners caregivers and servants Finally they explore the possibility that robots whether biological computational hybrids or pure machines should be given rights or moral consideration Ethics is often slow to catch up with technological developments This authoritative and accessible volume fills a gap in both scholarly literature and policy discussion offering an impressive collection of expert analyses of the most crucial topics in this increasingly important field Introduction to Autonomous Mobile Robots, second edition Roland

Siegwart,Illah Reza Nourbakhsh,Davide Scaramuzza,2011-02-18 The second edition of a comprehensive introduction to all aspects of mobile robotics from algorithms to mechanisms Mobile robots range from the Mars Pathfinder mission s teleoperated Sojourner to the cleaning robots in the Paris Metro This text offers students and other interested readers an introduction to the fundamentals of mobile robotics spanning the mechanical motor sensory perceptual and cognitive layers the field comprises The text focuses on mobility itself offering an overview of the mechanisms that allow a mobile robot to move through a real world environment to perform its tasks including locomotion sensing localization and motion planning It synthesizes material from such fields as kinematics control theory signal analysis computer vision information theory artificial intelligence and probability theory The book presents the techniques and technology that enable mobility in a series of interacting modules Each chapter treats a different aspect of mobility as the book moves from low level to high level details It covers all aspects of mobile robotics including software and hardware design considerations related technologies

and algorithmic techniques This second edition has been revised and updated throughout with 130 pages of new material on such topics as locomotion perception localization and planning and navigation Problem sets have been added at the end of each chapter Bringing together all aspects of mobile robotics into one volume Introduction to Autonomous Mobile Robots can serve as a textbook or a working tool for beginning practitioners Curriculum developed by Dr Robert King Colorado School of Mines and Dr James Conrad University of North Carolina Charlotte to accompany the National Instruments LabVIEW Robotics Starter Kit are available Included are 13 6 by Dr King and 7 by Dr Conrad laboratory exercises for using the LabVIEW Robotics Starter Kit to teach mobile robotics concepts

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